

ON THE BOOTSTRAP MULTIVARIATE EXPONENTIALLY WEIGHTED MOVING AVERAGE (BMEWMA) IN SETTING CONTROL LIMITS AND P-VALUES FOR INTERPRETING OUT OF CONTROL SIGNALS

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ABSTRACT

The effects of control limits that are too narrow increase the rate of false alarms, while those that are too wide may not be able to identify special causes of variability in any given process. It is of this view that control chart methodology that can detect small to moderate shifts in the mean vector should be developed so that the probability of detecting or not detecting false alarm rate should be minimized. The bootstrap multivariate exponentially weighted moving average is proposed in setting control limits, while p-value method was introduced to identify out of control signals.

Keywords: Quality characteristics, BMEWMA control chart, out-of-control signals, control limits, p-values.

INTRODUCTION

Many control charts have been proposed for multivariate data, with the most popular being multivariate Shewhart (Hotelling's X^2 and T^2) chart, the multivariate exponentially- weighted moving average (MEWMA) chart, and the multivariate cumulative sum (MCUSUM) chart (Aparisi et al., 2004; Montgomery, 2009; Mahmoud and Maravelakis, 2010). Multivariate Hotelling's T² charts monitor T^2 statistics that assume the distance between an observation and the scaled-mean established from the in-control data. It has the capability to identify large shifts only but not very good in identifying small as well as moderate shifts in process mean vector, hence the multivariate cumulative sum (MCUSUM). The multivariate cumulative sum (MCUSUM) method graphs the increasing arithmetic of deviations of the observation principles from a given point against time. A vital quality of the CUSUM method is that, it brings together all the information in the series of observation points. This makes the CUSUM method more responsive even to smaller mean out of control signals (Smiley and Keoagile, 2005; Champ and Jones-Farmer, 2007). However, the problems involve with the use of MCUSUM method is the violation of assumption of multivariate normality, hence the multivariate exponentially-weighted moving average (MEWMA) methods.

The multivariate exponentially weighted moving average (MEWMA) was introduced by (Lowry *et al.*, 1992) as an

annex of univariate exponentially weighted moving average (EWMA). The primary aim of MEWMA is to quickly identify small variations that are present in a process more rapidly than the Hoteling's T^2 and MCSUM methods for the fact that the charting scheme takes advantage of the knowledge from previous observations in any given process. In other words, the MEWMA control chart is good at detecting small shift in the mean vector (Lowry *et al.*, 1992). The chart uses the charting statistic:

$$T_i^2 = Z_i \sum_{Z_i}^{-1} Z_i; i = 1, 2, ...$$
 (1)

where

$$Z_{i} = \lambda x_{i} + (1 - \lambda) Z_{i-1}$$
(2)
and the covariance matrix is given by

$$\Sigma_{\mathsf{Z}_{i}} = \frac{\lambda}{2-\lambda} \left[1 - (1-\lambda)^{2i} \right] \Sigma \tag{3}$$

with the scalar charting constant λ , $0 < \lambda \le 1$ (which may be adjusted to change the weighting of the past observation). Z_i is the vector of observations at time i when $Z_0 = 0$. The MEWMA control chart often performs poorly when normal assumption is violated with common values of the charting constant greater than 0.05. The values acceptable for the charting constant are often very small, which means putting the majority of the weight on the past observations (instead of the most current), (Stoumbos and Sullivan, 2002; Lee and Khoo, 2006; Joner Jr. *et al.*, 2008). A new maximum exponentially weighted moving average control chart for monitoring process mean and dispersion was developed by Rabyk and Schmid (2016). An extended nonparametric exponentially weighted moving average sign control chart

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was proposed by Lu (2015). New exponentially weighted moving average control charts for monitoring process dispersion was introduced by Haq et al. (2015). The EWMA method for detecting mean differences of a longmemory process was studied by Brown and Moltchanova (2015).

Generally, most parametric multivariate quality control methods usually adopted in determining if a system is performing as intended or if there are some unnatural causes of variation upon an overall statistics. It has the benefit of being able to handle different quality characteristics at the same time. However, the problems involve in the use of parametric multivariate method is the violation of assumption of multivariate normality that is required for many charts (Jarrett and Pan, 2007; Champ and Aparisi, 2007). To tackle this problem, the nonparametric kernel density estimation (KDE) Hotelling's T^2 control method was proposed by Chou *et al.* (2001). Hotelling's T^2 control limits obtained from this method is carried out without considering the assumption of normality. But the problem with the use of KDE is that it desires determination of numerous statistics or parameters to have a complete construction of the method. These consist of kernel functions, smoothing statistic, as well as mathematical integration to established kernel distribution so as to obtain the control limit.

To address these limitations (Phaladiganon et al., 2011) proposed the percentile bootstrap method as a means of obtaining Hoteling's T^2 control limits assuming that the distribution is not multivariate normal. However, this method bootstrapped from Hotelling's T² statistic obtained by collapsing the multivariate data into univariate, and this will results to control limits that is good in detecting of large shift only. Also, this method did not address the issue of out of control signal, hence the proposed methods. Like the normal Hotelling's T^2 method, existing methods are good in detecting large shift but insensitive to small and moderate shifts in process mean vector. To reduce the problem of violating multivariate distributional assumption as well as avoiding the problem of not detecting small to moderate shifts in the process mean vector (Chou et al., 2001; Phaladiganon et al., 2011; Chatterjee, and Qiu, 2009; Adewara and Adekeye, 2012), this study proposes the bootstrap multivariate exponentially weighted moving average (BMEWMA) for obtaining control limit. The proposed method is a distributional free assumption based on the non-parametric control chart.

MATERIALS AND METHODS

Proposed Bootstrap Multivariate Exponentially-Weighted Moving Average (BMEWMA) for obtaining **Control Limit**

To reduce the abnormal behaviours observed when the multivariate distributional assumption is violated as well

as detecting small to moderate shift in any process; this study proposes the following procedure to obtain bootstrap multivariate exponentially weighted moving average control limits. Suppose there are d quality characteristics and each of the quality characteristic contains n set of observations (x_{ij}) (i = 1, 2, ..., n; j = 1, 2, ..., d) as can be summarized in the matrix below.

$$\begin{pmatrix} x_1 & x_2 & \cdots & x_d \\ x_{11} & x_{12} & \cdots & x_{1d} \\ x_{21} & x_{22} & \cdots & x_{2d} \\ & & \cdots & & \\ x_{n1} & x_{n2} & \cdots & x_{nd} \end{pmatrix}_{dxn}$$
(4)

If the matrix notations of dxn dimensions can be transposed as expressions bellow:

$$\begin{aligned} x_1 &= (x_{11}, x_{21}, \dots, x_{n1})'; \\ x_2 &= (x_{12}, x_{22}, \dots, x_{n2})'; \dots; \\ x_d &= (x_{1d}, x_{2d}, \dots, x_{nd})' \end{aligned}$$

The proposed bootstrap BMEWMA procedure for obtaining control limits is as follows:

STEP 1. Combine the sample sizes of x_1, x_2, \dots, x_d of the sets of observation such that:

 $x^{\bullet} = x_1^{\bullet}, \dots, x_d^{\bullet}$ with replacement in Step (1) as: $x_{11}^*, x_{21}^*, \dots, x_{n1}^*; x_{12}^*, x_{22}^*, \dots, x_{n2}^*; \dots; x_{1d}^*, x_{2d}^*, \dots, x_{nd}^*$ STEP 3. Repeat Step (2) a large number of times and obtain bootstrap replications as:

$$\begin{aligned} x^* &= x_{11}^{*(i)}, x_{21}^{*(i)}, \dots, x_{n1}^{*(i)}; x_{12}^{*(i)}, x_{22}^{*(i)}, \dots, \\ & x_{n2}^{*(i)}; \dots; x_{1d}^{*(i)}, x_{2d}^{*(i)}, \dots, x_{nd}^{*(i)}, \end{aligned}$$

where $(i^* = 1, 2, ..., B)$, and B > 1000. STEP 4. Estimate the bootstrap replication mean vector (\overline{x}) , bootstrap replication variance and covariance matrix (5[•]) of the bootstrap sample variables in Step (3) **STEP 5.** Obtain **BMEWMA** (T_i^{2*}) statistics from the dataset in Step (4) as

$$T_i^{2*} = Z_i^{*'} \sum_{Z_i}^{-1} Z_i^{*}, \tag{5}$$

(5)

where

$$Z_{i}^{*} = \lambda x_{1}^{*} + (1 - \lambda) Z_{i-1}^{*}$$
(6)

$$\sum_{\mathbf{Z}_{i}^{*}} = \frac{\lambda}{2-\lambda} \left[1 - (1-\lambda)^{2i} \right] \Sigma^{*}; 0 < \lambda \le 1$$
(7)

STEP 6. For $\mathbf{B} = 3000$, repeat the processes in Step (5) 3000 times by changing the values of $Z_{B} \& \sum_{Z_{P}}$ appropriately to obtain $T_1^{2*}, T_2^{2*}, \dots, T_B^{2*}$. STEP 7. Set the upper control limit such that in each of

the bootstrap statistic $(T_1^{2*}, T_2^{2*}, ..., T_B^{2*})$ arranged from the lowest to highest figure, determine the position of $B(1-\alpha)^{th}$ value such that: 01

$$= \frac{1}{B} \#\{(T_1^{2^*}, T_2^{2^*}, \dots, T_B^{2^*}) \le B(1 - \alpha)\}$$
(8)

STEP 8. From the control limit established in Step (7), determine those quality characteristics that are under control process from those that are out of control process. That is, if any T^2 statistic is greater than *CLprop.bmewma.*, declare that particular observation as out of control.

Proposed P-values Method in Identifying Out of Control Signals

The problem of identifying quality characteristic(s) that is(are) responsible for out of control signal(s) has been an issue in multivariate control charts (Runger *et al.*, 1996; Mason *et al.*, 1995; 1997; Das 2006; Guh 2007; Li *et al.*, 2013). A very useful approach in identifying out of control signal is to obtain the p-values of the Hotelling's T^2 statistic that reflect the contribution of each variable. Adopting Mason *et al.*, 1995, Step 1 and 2 were obtained while Step 3 and 4 where introduced to obtain their p-values.

STEP 1. For a d-dimensional vector of quality characteristics, the first row is expressed as:

$$T^{2} = T_{j,i; \forall j=1,i=j-1}^{2}, T_{j,i;\forall j=2,i=j-1,j-2}^{2}, \dots,$$
$$T_{j,i;\forall j=d,i=j-1,j-2,j-3,\dots,j-d}^{2}$$
$$= T_{1}^{2}, T_{2,1}^{2}, T_{3,1,2}^{2}, T_{4,1,2,3}^{2}, \dots, T_{d,1,2,3,\dots,d-1}^{2}$$

STEP 2. Obtain f-distribution for each of T_j^2 and $T_{j,i}^2$ terms such that:

$$T_{j}^{2} \sim \frac{c(n+1)(n-1)}{n(n-c)} f_{(c,n-c,\alpha)}, c = 1$$
; and
$$T_{j,i}^{2} \sim \frac{c(n+1)(n-1)}{n(n-c)} f_{(c,n-c,\alpha)}, c = 2, 3, ..., j-1$$

are used to check if the jth quality characteristic is conforming to the association with other quality characteristics or not.

STEP 3. Repeat Steps 1 and 2 for other rows based on the number of quality characteristics (d!) and obtain the distinct terms (d^*2^{d-1}) for both the unconditional ($T_{j,t}^*$) and conditional ($T_{j,t}^*$) terms.

STEP 4. Obtain the bootstrap p-values for each of T_{f}^{*} and $T_{f,t}^{*}$ terms such that:

where $P_{value(Exist. Boot.)}$ denotes the p-value from the existing method and $P_{value(BMEWMA)}$ denotes the p-value from the proposed method.

STEP 5. Use the various P_{values} in Step 4 to assess whether there is a significant difference or not. If $(P_{values(Exist.Boot, BMEWMA}) > \alpha)$ value, it means that T_{j}^{a} or $T_{j,t}^{a}$ is (are) not responsible for the out of control signal(s). But when $(P_{values(Exist.Boot, BMEWMA)} \leq \alpha)$ value, it means that T_{f}^{z} or $T_{f,t}^{z}$ is (are) responsible for the out of control signal(s).

Application to Numerical Example

By way of illustration, the bootstrap procedure presented is implemented for a set of data with equal sample sizes. The set of data were obtained from the production processing of Owel Industries Nig. Ltd., a Family Delight Pure Soya Oil Production Company in Ekpoma, Edo State, Nigeria. Four quality characteristics (X_1, X_2, X_3) and X_4) representing phosphoric acid (milliliters), water (liters), caustic soda solution (kg) and industrial salt (kg) respectively at the neutralizer stage, under which forty five samples were recorded as shown in Columns (X_1, X_2, X_3) X_3 and X_4) of Table 1. The choice of data used in this study is the presence of sub-standard product of cooking oil displayed in the local market in Nigeria. Another motivation is the challenges faced by Quality Control Managers to discover the quality characteristic that is liable for the abnormal control behaviors or stop the entire production process. Stopping the process will result to waste of material resources and continuing with the process without identifying the variable will lead to substandard product. The urge to solve these problems gave rise to this research work.

Test of Correlation Coefficient

Nevertheless, to apply any multivariate control chart methodology, there is need to know whether there is association among the four variables. From the given data, the statistics of mean vector (∞), variance covariance matrix (∞) and correlation matrix (r) are given as follows:

$$\bar{x} = \begin{bmatrix} 2451.2222\\ 89.0889\\ 26.6444\\ 5.5489 \end{bmatrix}, \\ s = \begin{bmatrix} 186363.813 & 172.389 & 370.672 & -16.141\\ 172.389 & 101.674 & 1.260 & -2.027\\ 370.672 & 1.260 & 7.962 & -0.112\\ -16.141 & -2.027 & -0.112 & 0.269 \end{bmatrix} \text{ and } \\ r = \begin{bmatrix} 1.0000 & 0.040 & 0.304^* & -0.072\\ 0.040 & 1.000 & 0.044 & -0.388^{**}\\ 0.304^* & 0.044 & 1.0000 & -0.076\\ -0.072 & -0.388^{**} & -0.076 & 1.0000 \end{bmatrix}$$

* Significant at 0.05 ** Significant at 0.01

The association matrix denoted that there is relationship among the variables, hence the need for implementing multivariate control chart method. The value of Hotelling's T^2 statistic is computed using the Visual Basic

Sample	X ₁	\mathbf{X}_2	X ₃	X ₄	T^2	Sample	X ₁	\mathbf{X}_2	X ₃	X ₄	T^2	Sample	X ₁	\mathbf{X}_2	X ₃	X_4	T^2
1	3000	94	30	5.3	2.5324	16	1050	70	20	6.2	15.6408	31	2450	88	24	5.3	1.3496
2	2850	90	28	5.6	0.9443	17	3000	82	30	6	3.5346	32	2680	96	26	4.9	2.0374
3	2300	92	24	5.4	1.0588	18	2850	80	30	5.2	3.7166	33	2750	100	22	6	7.3517
4	2500	80	25	5.2	2.499	19	2000	95	31	5	5.9975	34	2900	87	29	6.3	3.9443
5	2750	45	27	7.5	24.9818	20	2050	86	26	5.8	1.0593	35	2850	89	30	5.1	2.4777
6	2400	82	26	5.8	0.581	21	2150	91	25	5.7	0.803	36	2000	96	26	5.3	1.7141
7	1550	80	20	5.1	10.5469	22	2060	83	28	5.4	2.1454	37	3000	99	27	6.1	5.2445
8	2950	100	30	4.2	8.2502	23	2700	90	24	5.6	1.723	38	2150	100	28	6	5.9041
9	2850	93	29	6.1	3.271	24	2800	94	25	5.3	1.7413	39	2300	101	22	5.8	5.1479
10	2300	85	25	5.9	0.7641	25	2950	85	27	5.4	1.7658	40	2400	102	25	5.7	2.717
11	2250	95	24	5.5	1.3214	26	2250	86	29	5.4	1.549	41	2600	80	28	5.2	2.2793
12	2900	80	26	5.2	3.4108	27	2005	97	32	5.9	8.2599	42	2015	94	29	5.9	3.5712
13	2550	87	27	5.7	0.1649	28	2010	100	24	5.6	3.0063	43	2225	90	30	6	3.3235
14	2100	98	28	5.4	2.0423	29	3010	98	23	5	6.2249	44	2450	98	27	5.4	0.7971
15	2000	86	29	5	4.3045	30	2500	84	28	4.8	3.5793	45	2900	81	26	5.5	2.2492

Table 1. Family Delight Pure Soya Oil Production Data and T² Statistic

Table 2. Phaladigalon's Bootstrap Method Replicated from *T*² Statistic.

S/N	Bootstrap T ² Replicated											Percentile value		
5/11	1	2	3	4	5	•	•	•	41	42	43	44	45	100(1-α)
1	3.41	2.04	5.99	5.15	8.25				8.25	2.25	2.28	3.41	6.22	10.09
2	4.30	2.245	3.94	3.32	3.27				8.25	0.58	2.28	1.71	1.32	8.258
3	5.90	6.22	1.72	2.15	1.55				5.245	1.74	3.32	3.01	0.16	8.071
4	1.55	7.35	0.80	0.80	6.22				2.532	0.94	6.22	1.72	2.5	14.62
•										•		•		
•	•	•	•	•	•	•	•	•	•	•	•	•	•	•
		•	•	•	•				•	•		•	•	
2997	1.741	1.35	2.25	3.94	5.9				3.944	2.04	3.57	0.76	0.58	8.25
2998	5.245	3.72	2.15	8.26	5.15				5.148	3.57	5.9	3.58	6.22	15.64
2999	2.249	5.9	4.3	1.06	3.94				3.271	1.77	3.32	3.94	3.27	23.11
3000	4.305	2.28	3.72	5.24	3.41				1.321	0.8	6.22	1.06	0.76	6.179

Code (F-Distribution Form Code in the Appendix) for each sample and summarized in Table 1.

Using the existing method, bootstrap samples are replicated 3000 times from the Hotelling's T^2 statistic in Table 1, and $100(1-\alpha)$ percentile value computed for each sample is shown in Table 2.

However, the proposed bootstrap multivariate exponential weighted moving average (BMEWMA) procedures was implemented in Visual Basic Code (MEWMA Bootstrap Form Code in the Appendix) to obtain the bootstrap sample replicated 3000 times from the original data set and BMEWMA T^2 statistic is computed for each as shown in Table 3.

Table 4 shows the results of control limits obtained at $\alpha = 0.05$ level of significant from f-distribution, existing

bootstrap method and Step (9) from the proposed **BMEWMA** method, and the control chart is shown in Figure 1.

Identification of Out of Control Signal by P-value Method for Sample 16

Figure 1 shows that samples 5,7,8,16 and 27 are out of control, but we do not know which or set of quality characteristic(s) that is(are) responsible for the signal(s), hence the need to identify those quality characteristics by using the proposed p-value method. Focusing on Sample 16 by repeating Steps (1-4), Table 5 shows all the unconditional and conditional T^2 values and compared with their various p-values.

Sample	Y1	Y2	Y3	Y4	Z1	Z2	Z3	Z4	T^2	T ² Sorted
1	69.8891	-3.6446	0.9116	-0.0623	6.99	-33.26	0.75	-0.25	5.136	0.046
2	2.8891	-0.2446	0.2004	-0.1623	63.19	-3.3	0.84	-0.07	10.761	0.047
3	57.6669	2.2888	0.6671	-0.1268	8.37	0.01	0.25	-0.16	4.644	0.113
2850	-27.4442	-0.7334	-0.0884	0.0021	48.86	-0.47	0.57	-0.11	4.512	7.406
2851	-49.3331	-1.3557	-0.7551	-0.0379	52.77	-3.34	-0.26	0.05	6.523	7.415
				•						
2998	24.1113	-1.2668	-0.3329	-0.0223	-31.69	-2.35	-0.15	0.03	2.934	16.732
2999	-34.222	-0.2223	0.0671	0.051	70.98	-2.06	0.23	0	3.319	19.757
3000	-36.5553	0.7332	-0.2662	-0.0823	26.84	1.91	0.25	-0.04	2.401	24.534

Table 3. Bootstrap Sample Replicated and BMEWMA T^2 Statistic.

Table 4. Control Limits for the Different Methods at α Level of 0.05.

Alpha level (α)	F-Distribution	Existing Bootstrap Method	Proposed BMEWMA Method
0.05	11.4089	11.3314	7.406

RESULTS AND DISCUSSION

The value of control limit for f- distribution is given by $CL_F = 11.4089$, existing bootstrap method gives a CL_{Exist.Boot} = 11.3314 and that of proposed BMEWMA method gives $CL_{EMEWMA} = 7.406$ assuming $\alpha = 0.05$. Comparing these control limits in Table 4 with column T^2 in Table 1, out of control signals was detected when Samples 5, 7, 8, 16 and 27 were considered, and their positions are shown in Figure 1. Results in Table 4 shows that control limits obtained from both f-distribution and existing bootstrap methods were able to detect out of control signals for Samples 5 and 16, but consider Samples 7, 8 and 27 to be under control. This has demonstrated the ability of the two Hotelling's T^2 methods to detect large shift in the process mean vector. However, the proposed BMEWMA method was able to detect out of control signals in additional three Samples (7, 8 and 27), this has demonstrated the ability of the proposed method to detect small to moderate shift in any process.

From Table 5a, T_1^2 and T_2^2 of the four unconditional T^2 terms associated with Sample 16 are significant, which means X_1 (phosphoric acid) and X_2 (caustic soda) are responsible for the out of control signals individually.

However, results from existing p-values did not support this finding. To reduce the problem of out of control signal facing variables X_1 and X_3 , remove T_1^2 and T_2^2 separately from $T^2 = 15.6408$ of Sample 16 and compare with the control limits whether they are significant or not. i.e.

$$T^2 - T_2^2 = 15.6408 - 10.5354 = 5.1054 < 11.4689, 11.3336, 7.415$$

Hence, we conclude that variable X_1 is not significant. However, result obtain when T_2^* is removed from T^* shows that X_2 (caustic soda) is significant when compared with Control Limits from the proposed methods in Table 4, hence the next step, i.e.

$T^2 - T_2^2 = 15.6408 - 5.5435 = 10.1063 < 11.4689, 11.3336 > 7.415$

In Table 5b, the first conditional T^2 terms associated with Sample 16 shows that $T_{1...}^{*}T_{1...}^{*}T_{1...}^{*}T_{1...}^{*}$ of the twelve conditional T^2 terms have significant values, which means the relationship between X_1 (phosphoric acid) and X_2 (water); X_1 (phosphoric acid) and X_1 (caustic soda); X_1 (phosphoric acid) and X_4 (industrial salt) respectively are responsible for out of control signals. To reduced the problem of out of control signal facing these 1^{st} conditional variables, remove $T_{1...}^{*}$, $T_{1...}^{*}$, $T_{1...}^{*}$



Fig. 1. Multivariate Hotelling's T² Control Chart for the given Data

Table 5. Bootstrap P-values for Unconditional and Conditional T^2 Terms for Sample 16 Table 5a. Unconditional T^2 Terms with p-values (Number of $T_{sortd}^2 \ge T_f^2$ in Parenthesis)

T ² Component	Computed T_j^2 Value	F- Critical values	Existing Bootstrap P-Value	Proposed BMEWMA P-value	T ² _{<i>j</i>} Reduced (Sig./Not)
T ₁ ²	10.5354*	4.1519	0.421 (1263)	0.0127 ^{**} (38)	5.1054 (N/S)
T_{2}^{2}	3.5839	"	1.000 (3000)	0.3243 (973)	N/S
T ₃ ²	5.5435*	"	0.9973 (2992)	0.1263 (379)	10.1063 (Sig)
T_4^2	1.5760	"	1.000 (3000)	0.7407 (2222)	N/S

with the control limits whether they are significant or not. T_{12}^2, T_{14}^2 are not significant as shown in the last columns of Table 5b, while T_{12}^2 is significant, hence we move to the next step, i.e.

 $\begin{array}{l} T^2 - T^2_{12} = 15.6408 - 10.0702 = 5.5706 < 11.4689, 11.3336, 7.415 \\ T^2 - T^2_{12} = 15.6408 - 7.0501 = 8.5907 < 11.4689, 11.3336 > 7.415 \\ T^2 - T^2_{14} = 15.6408 - 9.9047 = 5.7361 < 11.4689, 11.3336, 7.415 \end{array}$

In Table 5c, the second conditional T^2 terms associated with Sample 16 shows that $T_{1,24}^2$ of the twelve conditional T^2 terms has significant value, which means the relationship between X_1 (phosphoric acid) and X_2 (water) and X_4 (industrial salt) are responsible for the out of control signals. To reduce the problem facing 2nd conditional variables, remove T_{124}^2 , from $T^2 = 15.6498$ of Sample 16 and compare with the control limits whether it is significant or not. T_{124}^2 is not significant as shown in the last columns of Table 5c, hence we stop the process, i.e.

 $T^2 - T_{1.24}^2 = 15.6408 - 9.8877 = 5.7531 < 11.4689, 11.3336, 7.415$ Since there is no more difference in Table 5c, Table 5d has no significant difference.

-7	Commuted	E Critical	Enciption of Department	Dronocod DMEW/MA	
$T_{j,i}^{z}$		F- Critical	Existing Bootstrap	Proposed BME wMA	L _j Reduced
Component	T _j i Value	values	P-Value	P-value	(Sig./Not)
T_{12}^2	10.0702^{*}	6.7247	0.5983	0.0147**	5.5706
1.4			(1795)	(44)	(N/S)
$T_{1,3}^{2}$	7.0501^{*}	"	0.95	0.0607	8.5907
			(2850)	(182)	(Sig)
$T_{1,4}^2$	9.9047*	"	0.5793	0.015**	5.7361
			(1738)	(45)	(N/S)
$T_{2,1}^{2}$	3.1186	,,	1.000	0.3977	N/S
			(3000)	(1193)	
$T_{2,2}^{2}$	3.2062	"	1.000	0.3833	N/S
			(3000)	(1150)	
$T_{2, \bullet}^2$	1.7200	,,	1.000	0.7067	N/S
			(3000)	(2120)	
$T_{2,1}^{2}$	2.0595	,,	1.0000	0.6183	N/S
			(3000)	(1855)	
$T_{2,2}^{2}$	5.1672	"	0.9983	0.1503	N/S
			(2995)	(451)	
$T_{2,4}^2$	5.0719	"	0.9987	0.1603	N/S
			(2996)	(481)	
$T_{4,1}^2$	1.0378	"	1.000	0.8613	N/S
			(3000)	(2584)	
$T_{4,2}^{2}$	0.2366	"	1.000	0.9943	N/S
			(3000)	(2983)	
$T_{4,2}^{2}$	1.1492	"	1.000	0.8397	N/S
-10			(3000)	(2519)	

Table 5b. 1st Conditional T^2 Terms with p-values (Number of $T_{Sortd}^2 \ge T_{j,i}^2$ in Parenthesis).

*Out of Control Signals **Significant at 0.05 N/S (Not Significant) (Sig) Significant ($T_{J-i}^2 > CL$)

CONCLUSION

This study specifically considered the BMEWMA method as a means of determining control limits from multivariate control charts. The intension is to reduce the rate of not discovering false alarm in any given process. Procedures that can carry out a systematic generation of bootstrap replications for two or more quality characteristics have been proposed in this work; it is straight forward but computer intensive. Using numerical example, control limits obtained from the proposed method performed very well when compared with the existing methods as shown in Table 4 and Figure 1, i.e.

 $CL_F = 11.4089$, $CL_{Exist.Boot} = 11.3314$ and $CL_{BMEWMA} = 7.406$; thereby ensuring reduction in the rate of not discovering false alarm. However, to identify the root cause of change when multivariate control charts signals, this work also considered the p-value as a means of identifying the variable(s) that is(are) responsible for the out of control signal(s). From Table 5a, computed T_{a}^{2} value is greater than F-critical value (i.e. 5.5435 > 4.1519); existing bootstrap p-value is greater than α value (i.e. 0.9973 > 0.05); and proposed bootstrap p-value is greater than α value (i.e. 0.1263 > 0.05), then the next stage in Table 5b. From Table 5b, computed T_{a}^{2} value is greater than F- critical value (i.e. 7.0501 > 6.7247); existing bootstrap pvalue is greater than α value (i.e. 0.95 > 0.05); and proposed bootstrap p-value is greater than α value (i.e. 0.0607 > 0.05), hence the next stage in Table 5c. In Table 5c, computed $T_{1,24}^2$ value is greater than F-critical value (i.e. 9.8877 > 9.0824); existing bootstrap p-value is greater than α value (i.e. 0.5793 > 0.05); and proposed bootstrap p-value is less than α value (i.e. 0.0153 > 0.05), hence no more significant value as experienced in Table 5d. Results from Tables 5a, b, c, d showed that the major problem lies on variable X_1 (phosphoric acid) and X_{a} (caustic soda) for Sample 16. The usual control chart practice method is to stop the entire process as a result of out of control signal at variable X_1 and X_3 this will result to waste of material resources or low quality/sub standard products if the process continuous. With the proposed multivariate methods, one variable is being conditioned on the other(s) as shown in Tables 5a, b, c, d. The implication of these findings is the advantages of multivariate control charts; by combining variable X₁ or X_3 with any other variables until there is no out of control signals as observed in Table 5d. This finding will enhance production process and avoid waste of material resources and improve the quality of product.

T ² _{j.i} Component	Computed T ² _{j,i} Value	F- Critical values	Existing Bootstrap P-Value	BMEWMA P-value	T ² _{j.i} Reduced (Sig./Not)
T ² _{1.23}	6.7966	9.0824	0.9517 (2855)	0.0713 (214)	N/S
$T^{2}_{1,24}$	9.8877*	"	0.5793 (1738)	0.0153 ^{**} (46)	5.7531 (N/S)
T ² _{1.34}	6.7769	"	0.9517 (2855)	0.0713 (214)	N/S
T ² _{2.13}	2.9527	"	1.000 (3000)	0.4267 (1280)	N/S
T ² _{2.14}	2.2076	"	1.000 (3000)	0.5827 (1748)	N/S
T ² _{2.34}	2.2200	"	1.000 (3000)	0.5803 (1741)	N/S
T ² _{3.12}	1.8936	"	1.0000 (3000)	0.6593 (1978)	N/S
T ² _{3.14}	1.9004	"	1.0000 (3000)	0.6587 (1976)	N/S
T ² _{3.24}	5.0236	"	0.999 (2997)	0.164 (492)	N/S
$T_{4,12}^2$	0.1377	"	1.000 (3000)	0.9983 (2995)	N/S
T ² _{4.13}	0.8895	"	1.000 (3000)	0.8927 (2678)	N/S
T ² _{4.23}	0.1766	"	1.000 (3000)	0.9967 (2990)	N/S

Table 5c. 2 nd Conditional T^2 Terms with p-values (Number of $T_{sortd} \ge T_{j,i}$ in Parenthesi	is)).
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*Out of Control Signals **Significant at 0.05 N/S (Not Significant) (Sig) Significant ($T_{J-i}^2 > CL$)

Table 5d. 3 rd C	Conditional T ²	Terms with	p-values	(Number of	$T_{Sortd}^{*} \geq$	T _{j.i} in	parenthesis).
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T ² _{j.i} Component	Computed $T_{j,i}^2$ Value	F-Critical values	Existing Bootstrap P-Value	BMEWMA P-value	T² <i>j.i</i> Reduced (Sig./Not)
T ² _{1.234}	0.8247	11.4088	1.0000 (3000)	0.906 (2718)	N/S
T ² _{2.134}	5.0433	"	0.5650 (1695)	0.141 (423)	N/S
T ² _{3.124}	0.0293	"	1.0000 (3000)	1.000 (3000)	N/S
T ² 4.123	5.3164	,,	0.9977 (2993)	0.141 (423)	N/S

*Out of Control Signals **Significant at 0.05 N/S (Not Significant) (Sig) Significant ($T_{J-i}^2 > CL$)

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APPENDIX. MULTIVARIATE BOOTSTRAP CONTROL SYSTEM Splash Screen Form



SplashScreen Form code

Private Sub tmrDisplay_Timer() Unload Me mdiMain.Show End Sub

Main Form



Main Form Code

Private Sub mnuAboutSoftware_Click() frmAbout.Show End Sub

Private Sub mnuBootstrap_Click() frmBootstrap.Show End Sub

Private Sub mnuBootstrapClearAll_Click() On Error Resume Next If formBoostrap = True Then DataEnv.ClearBoostrap DataEnv.rsBoostrap.Requery frmBootstrap.DataGrid.Refresh End Sub

Private Sub mnuBootstrapRealMEWMA_Click() frmMEWMABootstrap.Show End Sub

Private Sub mnuCloseWindow_Click() If ActiveForm Then Unload ActiveForm End Sub Private Sub mnuFDistributionClearAll_Click() On Error Resume Next If formFDistr = True Then DataEnv.ClearFDistribution DataEnv.rsF_T.Requery frmF_Distr.DataGrid.Refresh End Sub

Private Sub mnuFDistributionEmptyRows_Click() On Error Resume Next If formFDistr = True Then DataEnv.ClearEmptyRows DataEnv.rsF_T.Requery frmF_Distr.DataGrid.Refresh End Sub

Private Sub mnuFTDistribution_Click() frmF_Distr.Show End Sub

Private Sub mnuMEWMABootstrapClearAll_Click() On Error Resume Next If formMEWMABootstrap = True Then DataEnv.ClearMEWMABootstrap If formModifiedMEWMABootstrap = True Then DataEnv.ClearModifiedMEWMABootstrap DataEnv.rsMEWMABootstrap.Requery End Sub

Private Sub mnuMEWMAClearAll_Click() On Error Resume Next If formRealMEWMA = True Then DataEnv.ClearRealMEWMA DataEnv.rsRealMEWMA.Requery End Sub

Private Sub mnuRealMEWMA_Click() frmRealMEWMA.Show End Sub

Private Sub mnuSaveChanges_Click() On Error Resume Next With DataEnv .rsF_T.UpdateBatch adAffectAll .rsBoostrap.UpdateBatch adAffectAll .rsRealMEWMA.UpdateBatch adAffectAll .rsMEWMABootstrap.UpdateBatch adAffectAll End With End Sub

F-Distribution Form



F-Distribution Form Code

Exit Sub errorHandler: MsgBox Err.Description, vbCritical End Sub

Sub ClearTextboxes() For n = 0 To 99 Text1(n).Text = "" Next n End Sub

Private Sub DataGrid_Click() txtTotalRecord.Text = DataGrid.ApproxCount txtCurrentRecord.Text = DataGrid.Row + 1 End Sub

Private Sub Form_Resize() On Error Resume Next 'resize datagrid If Me.Width - DataGrid.Width > 0 Then DataGrid.Width = Me.Width - 9000 DataGrid.Height = Me.Height - 1900 End If End Sub

Private Sub Form_Unload(Cancel As Integer) formFDistr = False mdiMain.mnuFTDistribution.Checked = False End Sub

MEWMA Bootstrap Form



MEWMA Bootstrap Form Code

Dim mSum As Single, vSum As Single, Variance As Single, Mean As Single Dim covSum As Single, Covariance As Single, preZi As Single Dim MatrixLine(10, 10) As Single Dim MatrixInverse(10, 10) As Variant Option Explicit

Private Sub cmdSOLVE_Click() On Error Resume Next Call ComputeMean Call ComputeVarCov Call Build_Matrix Call Calculate_Inverse Call Calculate_Transpose Call Type_Result DataEnv.rsMEWMABootstrap.UpdateBatch adAffectAll End Sub

Private Sub DataGrid_Click() txtTotalRecord.Text = DataGrid.ApproxCount txtCurrentRecord.Text = DataGrid.Row + 1 End Sub